Mohammad Samin Yasar

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EDUCATION	University of Virginia , Charlottesville, Vir Ph.D. in Computer Engineering	rginia	Aug 2017 – Presen	
	Dissertation: Enabling Human-Robot Collaboration through Representation Learning			
	University of Virginia , Charlottesville, Vi	rginia	Aug 2022	
	M.Eng. in Computer Engineering		Apr 2011	
	BRAC University , Dhaka, Bangladesh B.Sc. in Electrical and Electronic Engineering		Apr 2015	
RESEARCH AND	Collaborative Robotics Lab, University o	f Virginia	Jan 2020 – Presen	
WORK	Project: Enabling Human-Robot Collaboratio			
EXPERIENCE	Led multiple projects between academia and industry on robot perception and robot control. Proposed novel sequence learning algorithms that advanced the state-of-the-art in human motion prediction, work d		otion prediction, work don	
	in collaboration with CCAM. Proposed a policy learning framework that interleaves planning with execution for robots, with performance improvemen over state-of-the-art, work done in collaboration with NEC Labs.			
	Dependable Systems and Analytics Lab , University of Virginia Project: Detecting Adverse Events in Robotic Surgery in Real Time		Aug 2017 – Dec 2019	
	Led cross-disciplinary research with surgeons	plinary research with surgeons and residents from UVA School of Medicine.		
	Proposed a safety monitoring system that deter			
	Simulated realistic surgical robot failure mode Graduate Teaching Assistant , University		Ian 2021 May 202	
	Course: Human-Robot Interaction	or virginia	Jan 2021 – May 202	
	Co-instructed the hands-on laboratory classes			
	Developed assignments and lesson plans for the			
AWARDS &	Conducted tutorial sessions and graded assign	nents.	Son 202	
AWARDS & RECOGNITION	UVA Graduate Endowed Fellowship Recognized for academic performance and res	earch productivity.	Sep 202	
	UVA Career Center Distinguished Mentor Recognized for supporting and mentoring UVA students in their career development.		Aug 2023	
	UVA Professional Development Award		Apr 2023	
	Awarded on the basis of Ph.D. impact, leadership and commitment to the UVA community.			
	UVA Engineering Research Symposium (UVERS) Selected to present my Ph.D. work in the highly selective research symposium.		Mar 2022, Mar 2023	
	Human Robot Interaction Pioneers Selected as one of the HRI Pioneers 2022 for ongoing work in developing algorithms for with humans.		Apr 2022 boots to fluently collaborate	
	Double Hoo Research Grant Award	oco provimity human robot collaboration	Mar 2022	
	Awarded for proposed research on enabling close-proximity human-robot collaboration. Second place, ECE Research Poster competition , University of Virginia		Sep 2018	
	Awarded for research merit and presentation.	period, envelopy of virginia		
SKILLS	Machine Learning/Deep Learning	Computer Skills		
	 TensorFlow 	 Programming Languages: P 	 Programming Languages: Python, Java, C, C++ 	
	 PyTorch 	 Code Instrumentation: LLVM, Pin 		
	 Scikit learn 	• Others: UNIX/Linux, BASH, LATEX		
	Robotics	Computer Vision/Image Proc	essing	
	• ROS	 OpenCV 		
	 Gazebo 	 Matlab 		
SELECTED PUBLICATIONS	 JOURNALS M. S. Yasar, M. M. Islam, and T. Iqbal, "Imprint: Interactional dynamics-aware motion prediction in teams using multimodal context," ACM Transactions on Human-Robot Interaction (Impact Factor: 5.36). Under review for Mino Revision, 2023. M. M. Islam, M. S. Yasar and T. Iqbal, "MAVEN: A Memory Augmented Recurrent Approach for Multimodal Fusion, IEEE Transactions on Multimedia (Impact Factor: 8.13), 2022. M. S. Yasar and T. Iqbal, "A Scalable Approach to Predict Multi-Agent Motion for Human-Robot Collaboration," IEEE 			
	 M. S. Yasar and T. Iqbal , "A Scalable Approa Robotics and Automation Letters (Impact Fact 		Robot Collaboration," IEE	

TRAVEL GRANTS	AAMAS Travel Grant HRI Travel Grant DSN Travel Grant ISMR & SSMR Travel Grant	2023 2022 2019 2019
	 Wesley Lewis (CS Undergrad) Robotics Institute Summer Scholar (RISS), Carnegie Mellon University 2023. Dean's Summer Research Fellow 2022. Brandon Yang (CS Undergrad) Dean's Summer Research Fellow 2023. 	
MENTORING EXPERIENCE	TJ Vitchutripop (CS Undergrad) Robotics Institute Summer Scholar (RISS), Carnegie Mellon University 2023. Louis T. Rader Outstanding Undergraduate Research Award 2023. Double Hoo Research Grant Award 2022.	
	 Data-driven interface for detecting fraudulent transactions (Code) Design a pipeline for data preprocessing and feature selection tailored for an unbalanced dataset. Trained and validated different classifiers (kNN, SVM, XGBoost, Random Forest) using double cross va Product Price Prediction from Images (Code) Implemented a web crawler to create a dataset comprising of product images and product meta data. Designed a product price predictor consisting of a pre-trained model extracting visual features. Developed a fully-connected regressor for accurate product price prediction. 	
PROJECTS	 Extracted Histogram of Oriented Gradients (HOG) features from the initial video frame's designated terr Trained a linear SVM classifier for subject discrimination. Distinguished subject from background using distinctive HOG features. Employed sliding window technique for spatial analysis in video frames. Development of a surgical robot simulator (Code) Developed a surgical robot simulator integrating the gazebo physics engine. Achieved accurate replication of RAVEN II surgical procedures within a controlled virtual environment. Introduced a virtual camera perspective, enabling recording of experiments from the surgeon's point of v 	-
SERVICE ACADEMIC	Session Co-Chair: IEEE ICRA: Human-Robot Interaction Motion Planning Reviewer: ACM/IEEE International Conference on Human-Robot Interaction (HRI) Reviewer: ACM/IEEE International Conference on Human-Robot Interaction (HRI) Reviewer: IEEE Robotics and Automation Letters (RA-L) Reviewer: IEEE International Conference on Robotics and Automation (ICRA) Subject detection and tracking in a video (Code)	2021 2021 2021 2021, 2022 2020
SELECTED TALKS	 AAMAS - CoRaL: Continual Representation Learning for Overcoming Catastrophic Forgetting DC-AAMAS - Learning Transferable Representations for Non-Stationary Environments UVERS - Learning Transferable Representations for Non-Stationary Environments HRI Pioneers Workshop - Robots That Can Anticipate and Learn in Human-Robot Teams ICRA - A Scalable Approach to Predict Multi-Agent Motion for Human-Robot Collaboration LEAP-HRI - Improving Human Motion Prediction Through Continual Learning ISMR - Context-aware monitoring in Robotic Surgery Organizer: RSS Workshop on Close-Proximity Human-Robot Collaboration 	Jun 2023 Jun 2023 Mar 2023 Mar 2022 Jun 2021 Mar 2021 Apr 2019 2022
	 S. M. Preum, S. Munir, M. Ma, M. S. Yasar, D. J. Stone, R. Williams, H. Alemzadeh, J. A. Stankov of Cognitive Assistants for Healthcare: Trends, Prospects, and Future Directions," ACM Computing S Factor: 14.32), 2021. CONFERENCES M. S. Yasar, and T. Iqbal, "VADER: Vector-Quantized Generative Adversarial Network for Moti IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2023. M. S. Yasar, and T. Iqbal, "CoRaL: Continual representation learning for overcoming catastropi International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2023. M. S. Yasar, and H. Alemzadeh, "Real-Time Context-aware Detection of Unsafe Events in Robot-Ass: 50th Annual IEEE/IFIP International Conference on Dependable Systems and Networks (DSN), 2020. K. Hutchinson, M. S. Yasar, H. Bhatia and H. Alemzadeh, "A Reactive Autonomous Camera System fo Surgical Robot," International Symposium on Medical Robotics (ISMR), 2020. M. S. Yasar, D. Evans and H. Alemzadeh, "Context-aware Monitoring in Robotic Surgery," International Medical Robotics (ISMR), 2019. 	on Prediction," hic forgetting," sisted Surgery," r the RAVEN II